

Finger Search Trees with Constant Insertion Time

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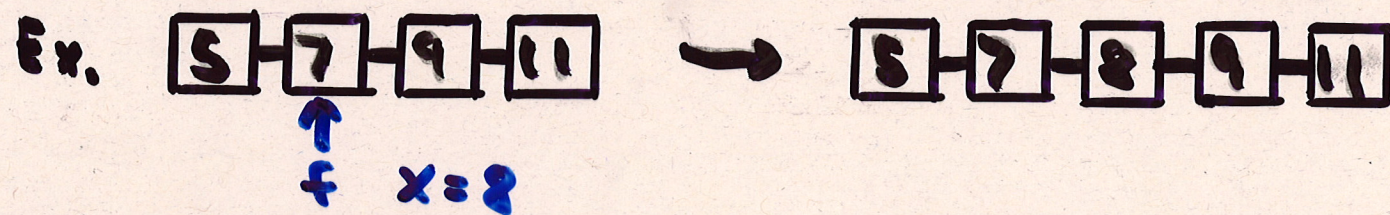
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*Supported by the  foundation

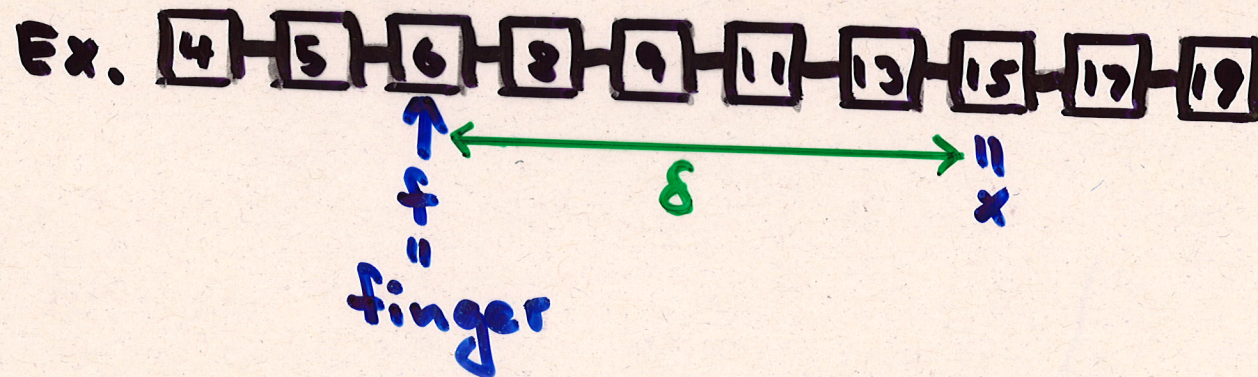
The Problem

Maintain a **Sorted List** of elements under

- **Insert(f, x)**, insert x to the right of f .

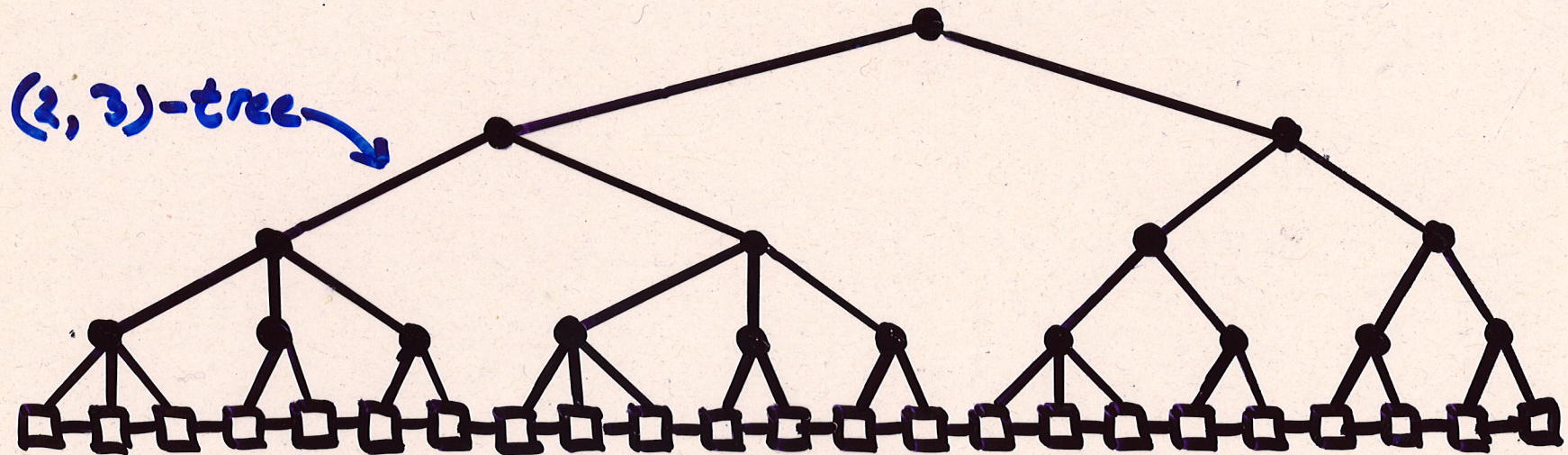


- **Search(f, x)**, search for x in the list starting at f .



A Simple Finger Search Tree

Brown, Tarjan 1980

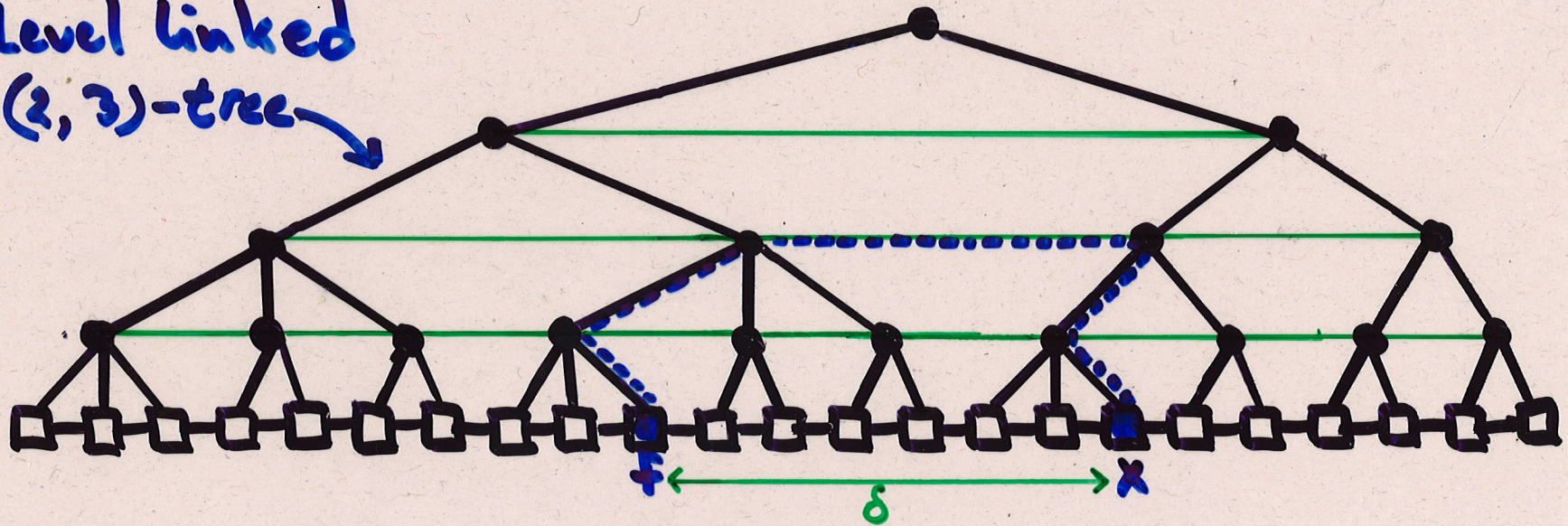


Insert : Amortized $O(1)$

A Simple Finger Search Tree

Brown, Taijan 1980

Level linked
(2, 3)-tree

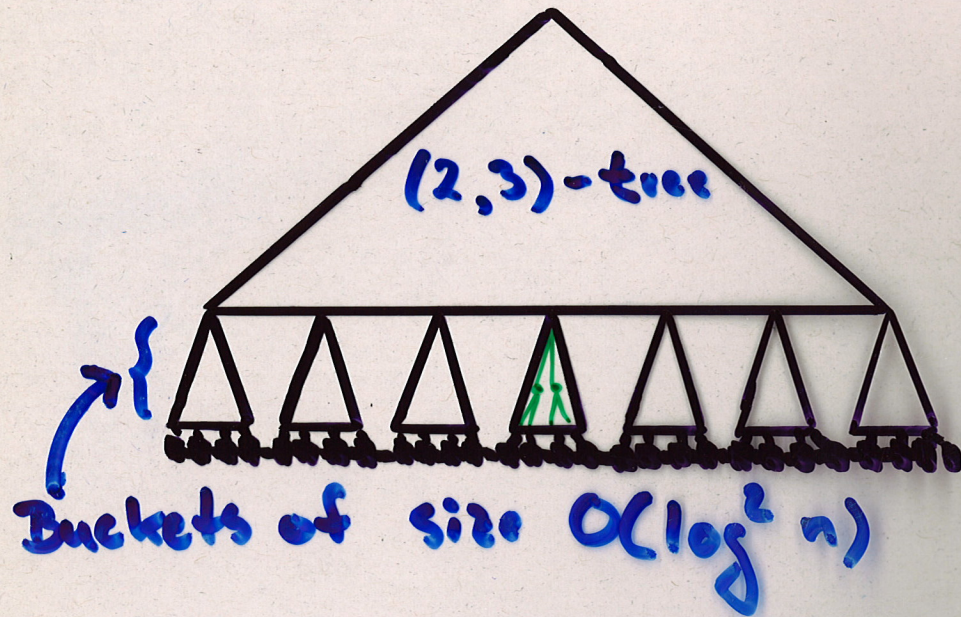


Insert : Amortized $O(1)$.

Search : Worst-case $O(\log \delta)$.

Search Trees With Constant Insertion Time

Levcopoulos, Overmars 1988



Idea

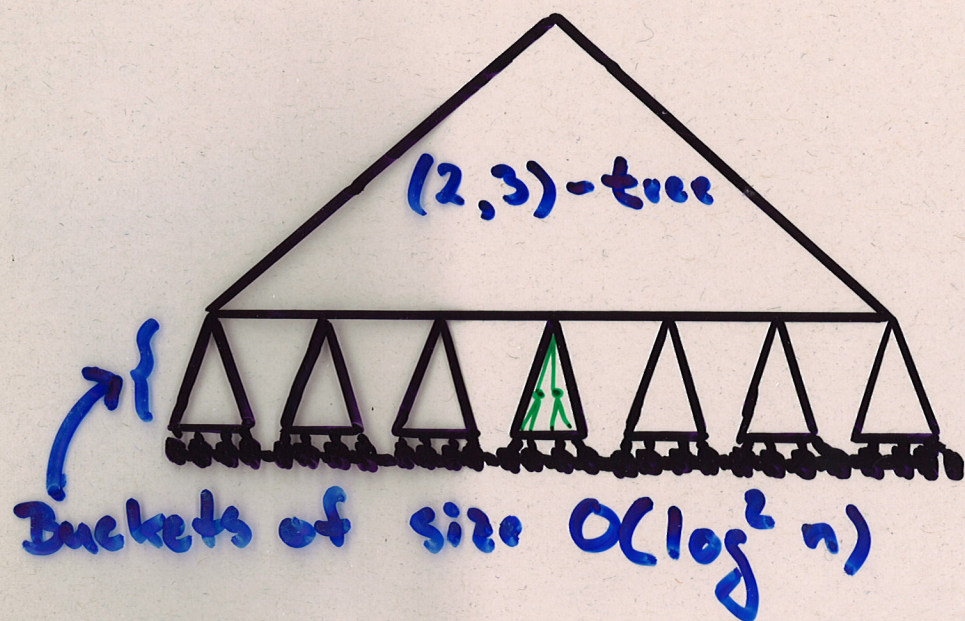
For every $\log n$ th insertion split the largest bucket and update the (2,3)-tree over the next $\log n$ insertions.

Insert : $O(1)$

Search : $O(\log n)$

Search Trees With Constant Insertion Time

Levcopoulos, Overmars 1988



Idea

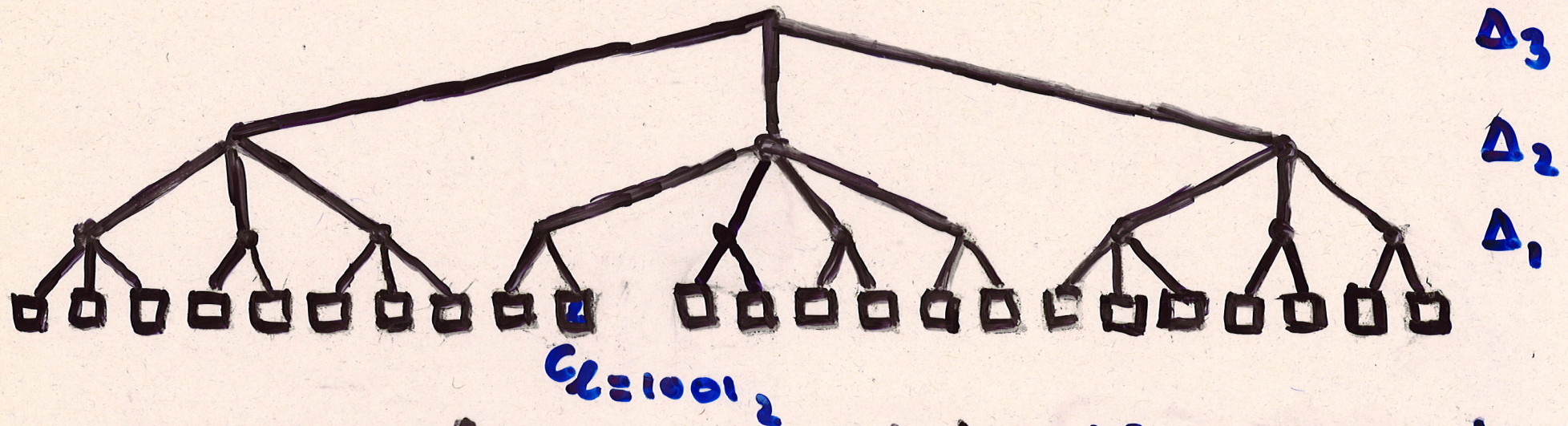
For every $\log n$ th insertion split the largest bucket and update the (2,3)-tree over the next $\log n$ insertions.

	1 recursive	$\log^* n$ recursive
Insert :	$O(1)$	$O(\log^* n)$
Search :	$O(\log \log n + \log \delta)$	$O(\log \delta)$

Previous Work

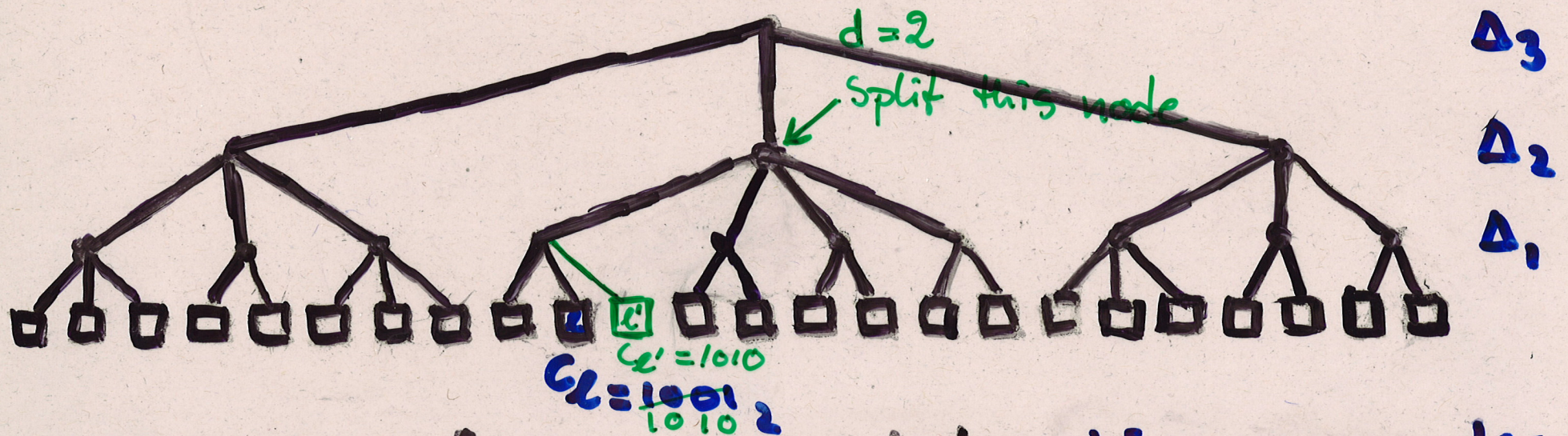
	Insert	Search	
Search Trees	$\log n$	$\log n$	
Leucopoulos, Overmars 1988	1	$\log n$	
Brown, Tarjan 1980	1	$\log \delta$	Amortized insertions
Dietz, Raman 1994	1	$\log \delta$	Requires the RAM
Harel, Lueker 1979	$\log^4 n$	$\log \delta$	
Guibas et al. 1977	1	$\log \delta$	$O(1)$ fixed fingers
→ Brodal 1997	1	$\log \delta$	Pointer Machine

A New Algorithm for Splitting Nodes in a Search Tree



- To each Leaf x is associated a binary counter C_x .
- All nodes of height d have degree at least Δ_d .

A New Algorithm for Splitting Nodes in a Search Tree



- To each leaf l is associated a binary counter C_l .
- All nodes of height d have degree at least Δ_d .

Insert(l, l')

1. $C_{l'} := C_l + 1$, $C_l := C_l$
2. Find d such that $C_l \bmod 2^d = 2^d - 1$
3. Split the d 'th ancestor of l

Main Lemma

Lemma All nodes of height d have degree $\leq 2^{2 \cdot 2^d} \Delta_d$.

Proof: Define $\Phi_\ell^d = 2^{2^d} - 1 - ((\ell + 2^{d-1}) \bmod 2^d)$

Define $\Phi_v^d = \sum_{\ell \in T_v^d} \Phi_\ell^d$

Invariant $\Phi_v^d \leq 2^{2 \cdot 2^d} \prod_{i=1}^d \Delta_i$

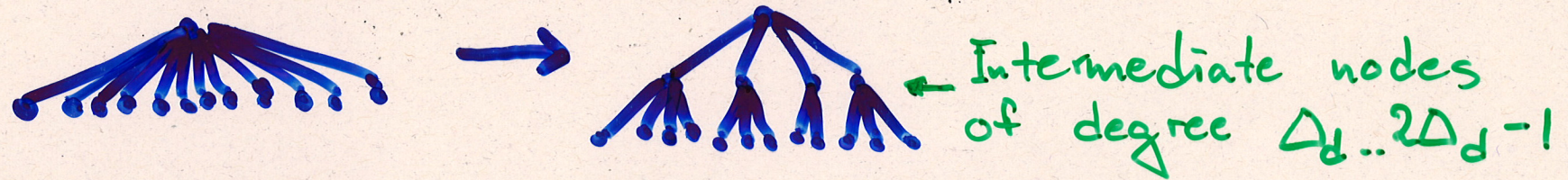
provided $\Delta_d \geq 2^{2^d} - 1$

The lemma follows from $|T_v^d| \geq \prod_{i=1}^d \Delta_i$. $\square$

Minor Problems to Solve

- 1) How to split a node of non constant degree in worst-case constant time?

Do the splitting incrementally in advance.



- 2) How to perform finger searches?

a) Level link the tree
b) Represent the children of each node by the search tree of Levcopoulos, Overmars 1988

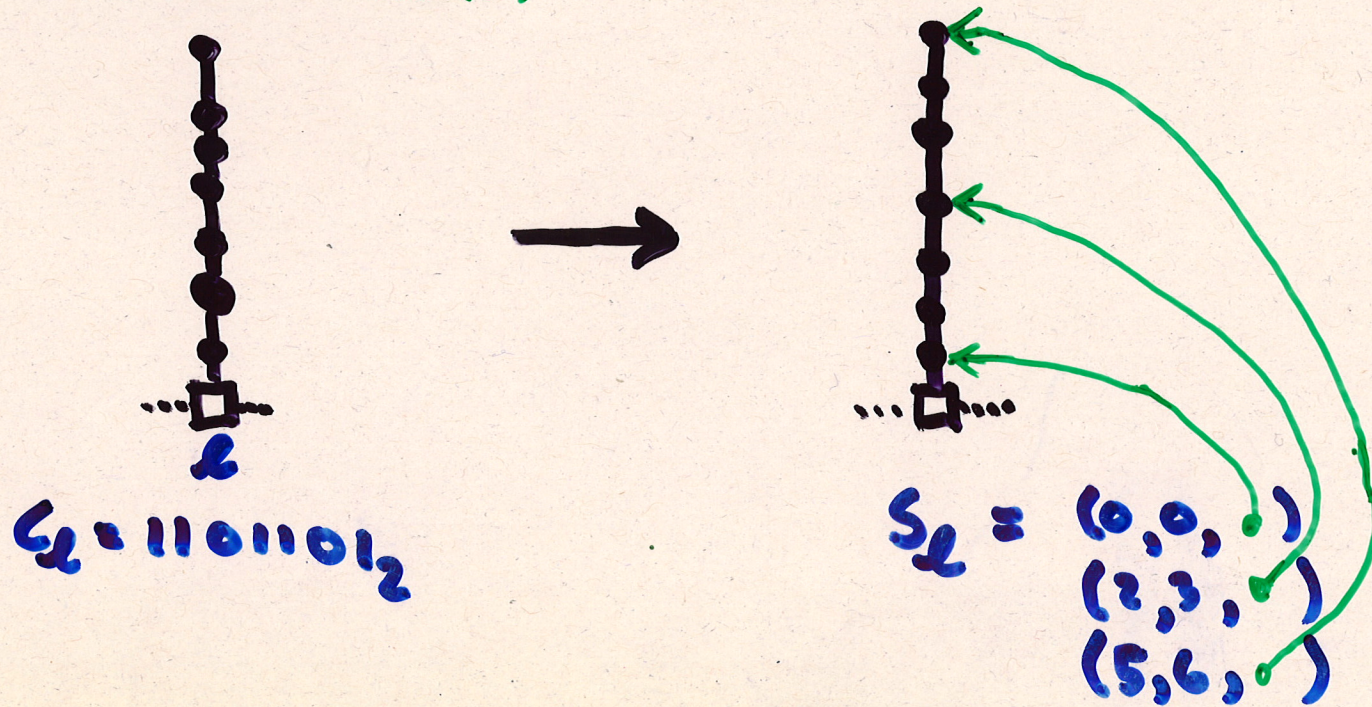
⇒ Finger Searches require $O(\log S)$ time.

A Major Problem to Solve

3) How to find the level d ancestor of a node?

- a) Represent each counter c_ℓ by a stack S_ℓ of intervals of 1's
- b) With each interval (i, j) in S_ℓ store a pointer to the $j+1$ 'st ancestor of ℓ .

⇓
 S_ℓ can be updated ($c_\ell := c_\ell + 1$) and the d 'th ancestor of ℓ can be found in worst-case constant time.



More Minor Problems To Solve

- 4) How to copy $S_L := S_L$ in worst-case constant time?

Let the stacks be functional implemented.

- 5) Splitting a node can make S_L stacks contain pointers to wrong subtrees!

Don't worry! A height d node has degree $\leq 2^{3 \cdot 2^d} \Delta_d$

Conclusion and Open Problems

Thm A pointer based implementation of finger search trees exists, supporting:

Insert in worst-case $O(1)$ time, and

Search — " — $O(\log S)$ time.

The data structure requires linear space.

Delete can be supported in worst-case $O(\log^* n)$ time.

Open problems

- Delete in $O(1)$ too.
- Make other splitting based data structures worst-case.
 - ex. Full Persistence.
 - Dynamic Fractional Cascading.