

Linear Haskell: some hows and whys

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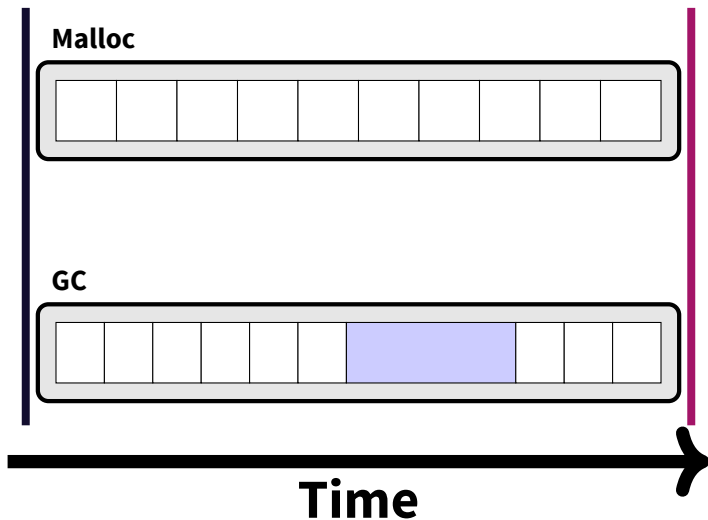


Idea → Joke → Let's do it!

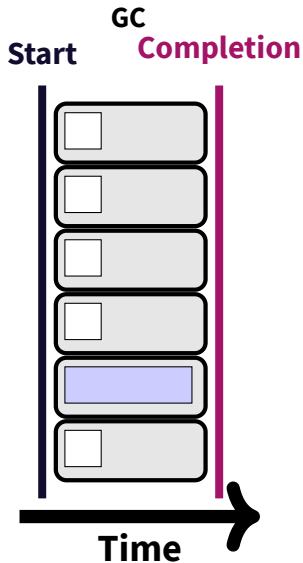
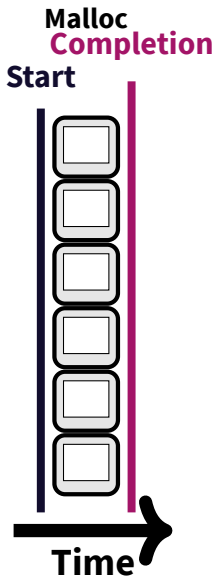
Let's talk about garbage collection

Start

Completion



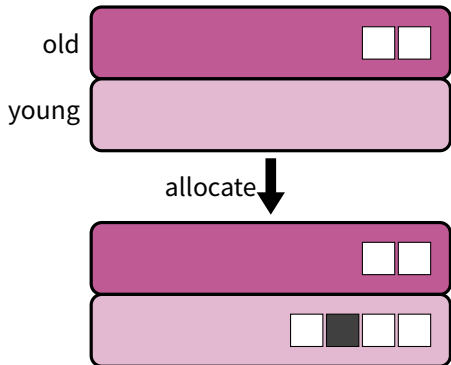
Garbage collection, latency, synchronisation



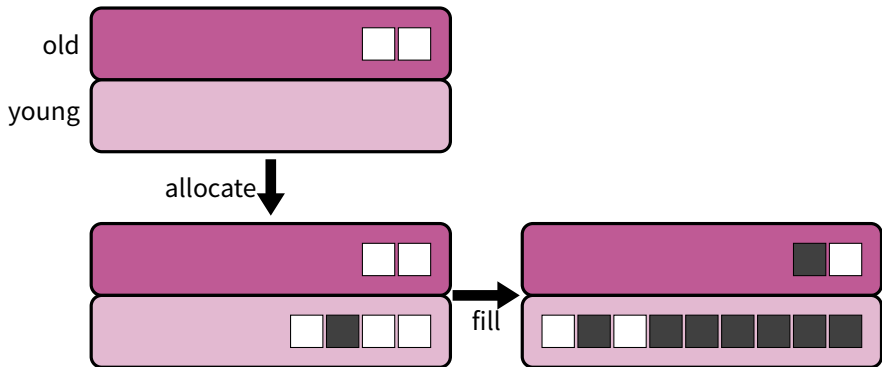
Generational hypothesis



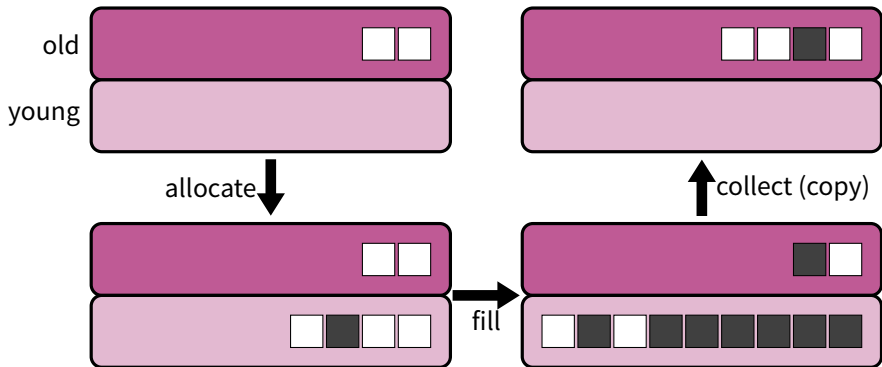
Generational hypothesis



Generational hypothesis



Generational hypothesis



Manual memory management

```
data Se82
```

```
do let (x :: Se82) = init  
      doSomething x
```



```
data Se82
```

```
do (x :: Se82) ← malloc  
   doSomething x  
   free x  
   doMore x
```

Manual memory management

```
data Se82
```

Don't forget to free!

```
do {  
  ...  
  doSomething x  
}
```

```
data Se82
```

```
do (x :: Se82) ← malloc  
  doSomething x  
  free x  
  doMore x
```

Don't use x anymore!

Again in the fields of x!



A linear function

```
SUCC :: Int → Int  
SUCC i = i + 1
```

```
repeat :: Int → [Int]  
repeat n = n : repeat n
```

```
constFalse :: Int → Bool  
constFalse n = False
```

Not linear functions

Linear functions

```
f :: Bool -> Int -> Int  
f b i = if b then i + 1 else i + 2
```

```
k :: Int -> (Int, Bool)  
k i = (i, True)
```

```
g :: Int -> [Int]  
g n = 42 : repeat n
```

```
h :: Bool -> Int -> Bool  
h b i = if b then i + 1 else 57
```

Not linear functions

Malloc: revisited

data IO_1 a

$(\gg=)$:: IO_1 a \multimap (a \multimap IO_1 b) \multimap IO_1 b — must be linear

malloc :: **Storable** a \Rightarrow IO_1 (Ptr a)

free :: **Ptr** a \multimap ()

Malloc: revisited

data IO_1 a

$(\gg=)$:: IO_1 a \multimap (a \multimap IO_1 b) \multimap IO_1 b — must be linear

malloc :: **Storable** a \Rightarrow IO_1 (Ptr a)

free :: **Ptr** a \multimap ()

do (x ::₁ **Se82**) \leftarrow malloc

x' \leftarrow doSomething x — doSomething doesn't free x

free x' — we can't forget free

doMore — x isn't available in doMore

Malloc: re²visited

malloc :: Storable a ⇒ a → (Ptr a → U a) → U a
free :: Ptr a → ()

malloc init \$ λ(x ::₁ Se82) →
 let x' = doSomething x in
 free x' `seq` doMore

What we've learnt so far

- GC pauses are costly in distributed settings
- Generational hypothesis: younger data dies sooner
 - Old heap collection causes the pauses
- Long-lived data contribute to pauses: we can manage them manually
 - Can be done safely with linear types

What we've learnt so far (and one thing we haven't)

- GC pauses are costly in distributed settings
- Generational hypothesis: younger data dies sooner
 - Old heap collection causes the pauses
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 - Can be done safely with linear types

A new idea

- Prevent data from moving to the old heap
 - Allocate fewer short-lived data too

GHC: rules

$\text{map } f \text{ (map } g) \text{ l} \rightsquigarrow \text{map } (f \circ g) \text{ l}$

$\text{foldr } k \text{ z (build } g) \rightsquigarrow g \text{ k z}$

Vector: stream fusion (mostly inlining)

$\text{stream (unstream } s) \rightsquigarrow s$

$\text{unstream (stream } v) \rightsquigarrow \text{clone } v$

Should I allocate?

`replicate :: Int → a → Vector a`
— Relies on stream fusion

Should I allocate?

What if you're writing to a file (memory map)?

What if the size is known up the pipeline?

replicate :: Int → a → Vector a
— Relies on stream fusion

What if the consumer is a foreign function?

What if you're writing to another computer (RDMA)?

What if the consumer isn't inlined?

Destination-passing style

`replicate :: Int → a → MVector a → ()`

Destination-passing style

replicate :: Int → a → MVector a → ()



I should use ST or IO

Destination-passing style

```
replicate    :: (MonadPrim m)
              => a -> MVector (PrimBase m) a -> m ()

mmap        :: FilePath -> IO (MVector Word8)
unsafeFreeze :: (MonadPrim m)
              => MVector (PrimBase m) a -> m (Vector a)
```


Destination-passing style

replicate :: a → DVector a → ()

split :: Int → DVector a → (DVector a, DVector a)

mmap :: FilePath → IO₁ (DVector a)

alloc :: (DVector a → ()) → Vector a

data Tree where

Node :: (Tree, Tree) \rightarrow Tree

Leaf :: Int \rightarrow Tree

nodeD :: **D** Tree \rightarrow (**D** Tree, **D** Tree)

leafD :: **D** Tree \rightarrow **D** Int

data [a] where

(:) :: (a, [a]) \rightarrow [a]

[] :: () \rightarrow [a]

consD :: **D** [a] \rightarrow (**D** a, **D** [a])

nilD :: **D** [a] \rightarrow ()

A tale of recursive maps

```
fill    :: a -> D a -> ()  
alloc  :: (D [a] -> ()) -> [a]  
  
consD  :: D [a] -> (D a, D [a])  
nilD   :: D [a] -> ()
```

```
map :: (a -> b) -> [a] -> [b]  
map f l = alloc $ \d -> loop l d
```

where

```
loop :: [a] -> D [b] -> ()  
loop [] d = nilD d  
loop (a:l) d = fill (f a) db `seq` loop l dr  
  where (db, dr) = consD d
```

A tale of recursive maps

```
fill    :: a -> D a -> ()  
alloc  :: (D [a] -> ()) -> [a]  
  
consD  :: D [a] -> (D a, D [a])  
nilD   :: D [a] -> ()
```

map :: (a -> b) -> [a] -> [b]

map f l = alloc \$ \d -> nilD (foldl' step d l)

where

step :: D [b] -> a -> D [b]

step d a = fill (f a) db `seq` dr

where (db, dr) = consD d

Representation

```
data [a] = Slice { base :: MArray a, offset :: Int, last :: IORef Int }
```

```
nilD l = unsafePerformIO $ writeIORef (last l) (offset l)
```

```
consD l = ((base l, offset l), l { offset = offset l + 1 })
```

```
fill a (l, offset) = unsafePerformIO $ writeArray l a
```

```
listView :: [a] → Maybe (a, [a])
```

```
pattern (a : l) ← Just (a, l) ← listView
```

```
pattern [] ← Nothing ← listView
```

Facilities offered by the compiler

- Garbage collection
- Fusion
- Data representation

You don't have to think about them.


But when you need to think about them, the compiler is no help.


- With linear types you can take them safely back in your own hands

A programming language is low level when its programs require attention to the irrelevant.

— Alan Perlis


Follow the adventures of Linear Haskell

 tweag.io/blog

 github.com/tweag/ghc/tree/linear-types

 github.com/tweag/linear-types

 <https://github.com/ghc-proposals/ghc-proposals/pull/111>

 <https://ghc.haskell.org/trac/ghc/wiki/LinearTypes>