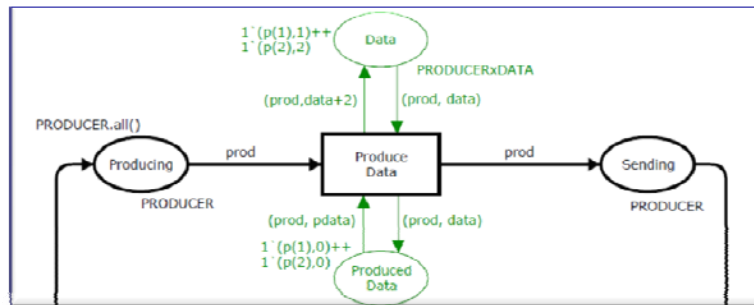


Towards Automatic Code Generation from Process Partitioned Coloured Petri Nets



```

- module (producer) .
- export ([start/2]) .
- record (environment, {
  produced_data,
  data}) .

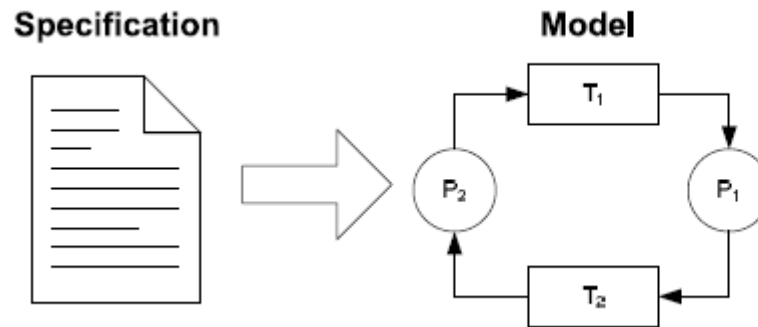
produce_data (Env) ->
  Data = Env#environment.data,
  NewEnv = Env#environment {produced_data = Data,
    data = Data + 2},
  send_data (NewEnv) .
  
```

K.L. Espensen, M.K. Kjeldsen, M. Westergaard
 Computer Science Department,
 Aarhus University, Denmark

L.M. Kristensen
 Department of Computer Engineering,
 Bergen University College, Norway

Motivation and Background

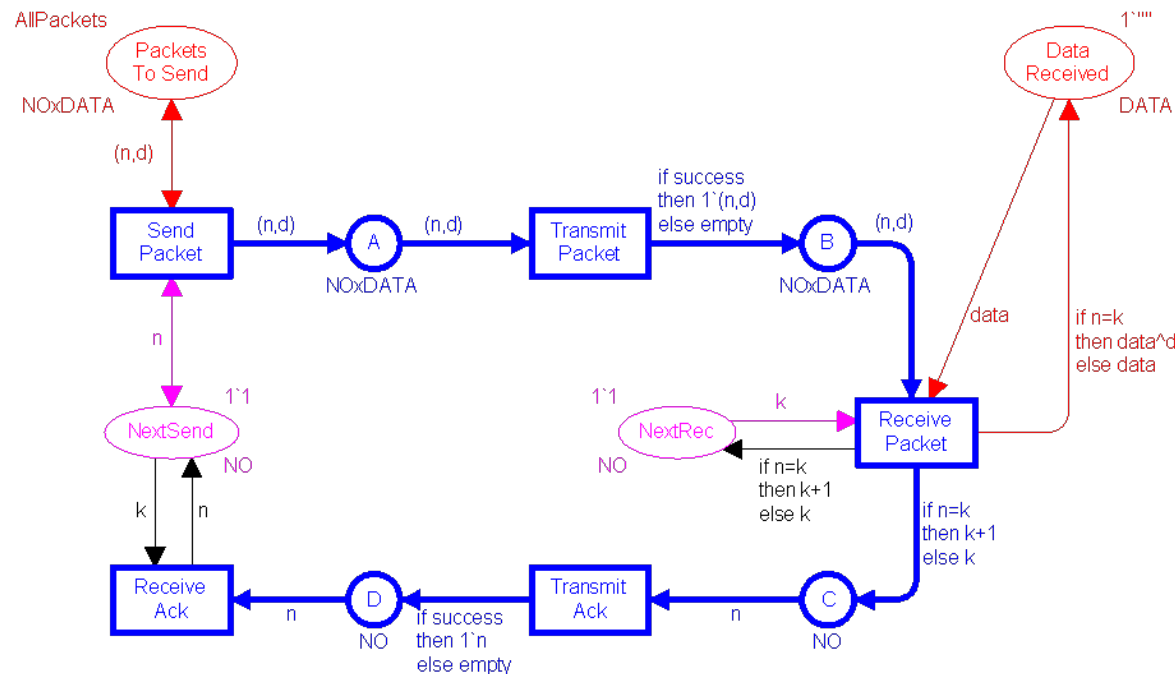
- Modelling, simulation, and analysis yields useful insight into the **design** and **behaviour** of a system:



- Several approaches to **automatic code generation**:
 - **Simulation-based**: the code constituting the model simulator is embedded directly in the implementation.
 - **State space-based**: the state space of the model is computed and used in the implementation.
 - **Structure-based**: structural analysis of the model for translation into programming language constructs.

An Observation (A Claim)

- It is difficult (generally) to recognize programming language constructs in CPNs:



Control flow: if-then-else, case, while, ...?

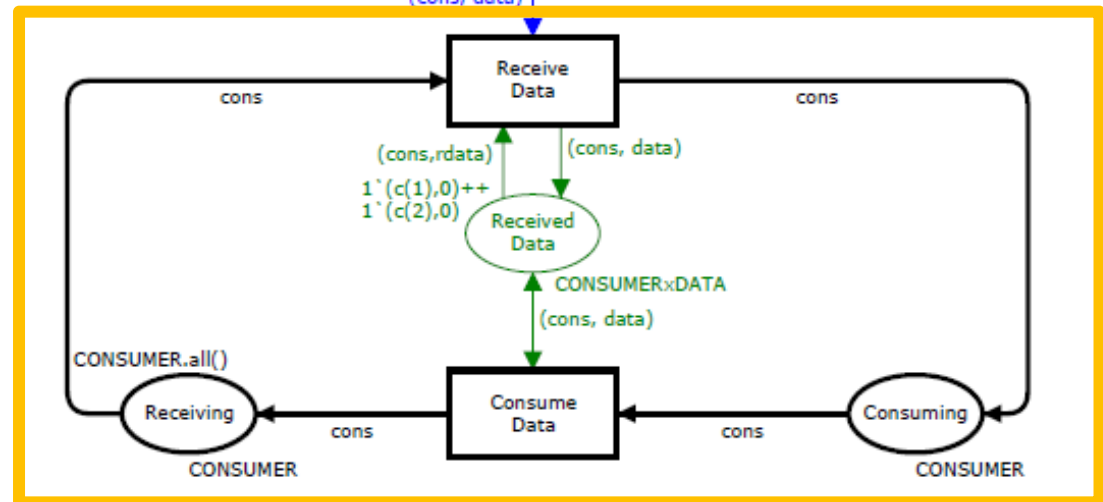
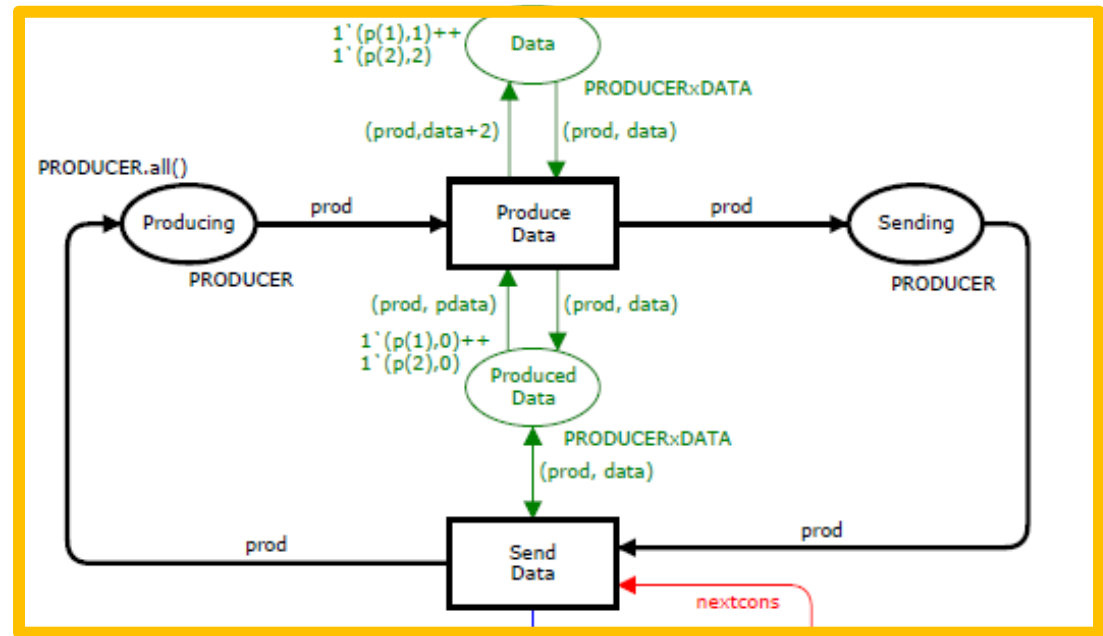
Communication, synchronisation, message passing, shared data, ...?

- Conclusion:** Some additional syntactical constraints and annotations are needed.



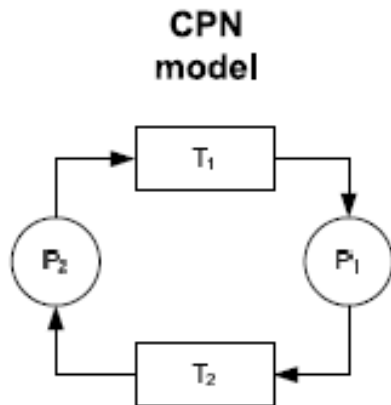
Process Partitioned CPNs

- Provides an explicit separation of:
 - Control flow of processes.
 - Message passing.
 - Shared and local data.
- Key concepts:
 - Process partitions and process places.
 - Buffer places.
 - Shared and local places.



Approach: Overview

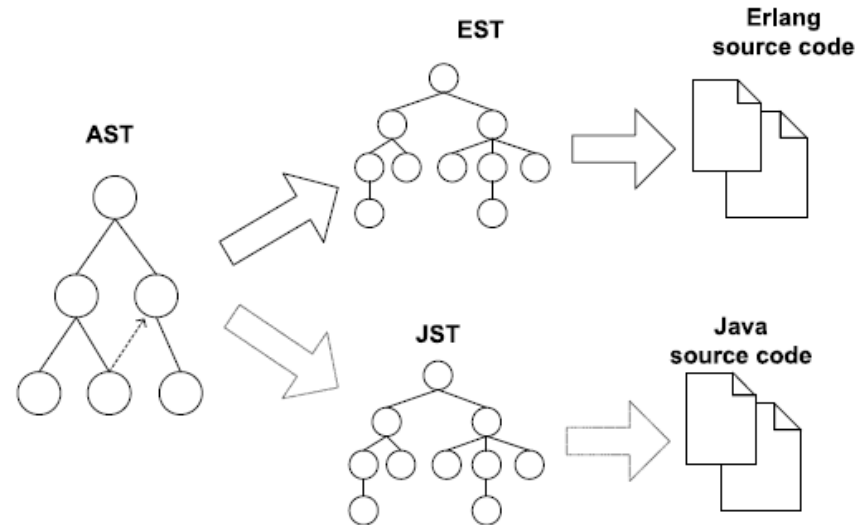
- The translation of Process-Partitioned CPNs into an implementation is divided into **phases**:



- The abstract syntax tree (AST) is independent of a particular target programming language.

Target Implementation Language

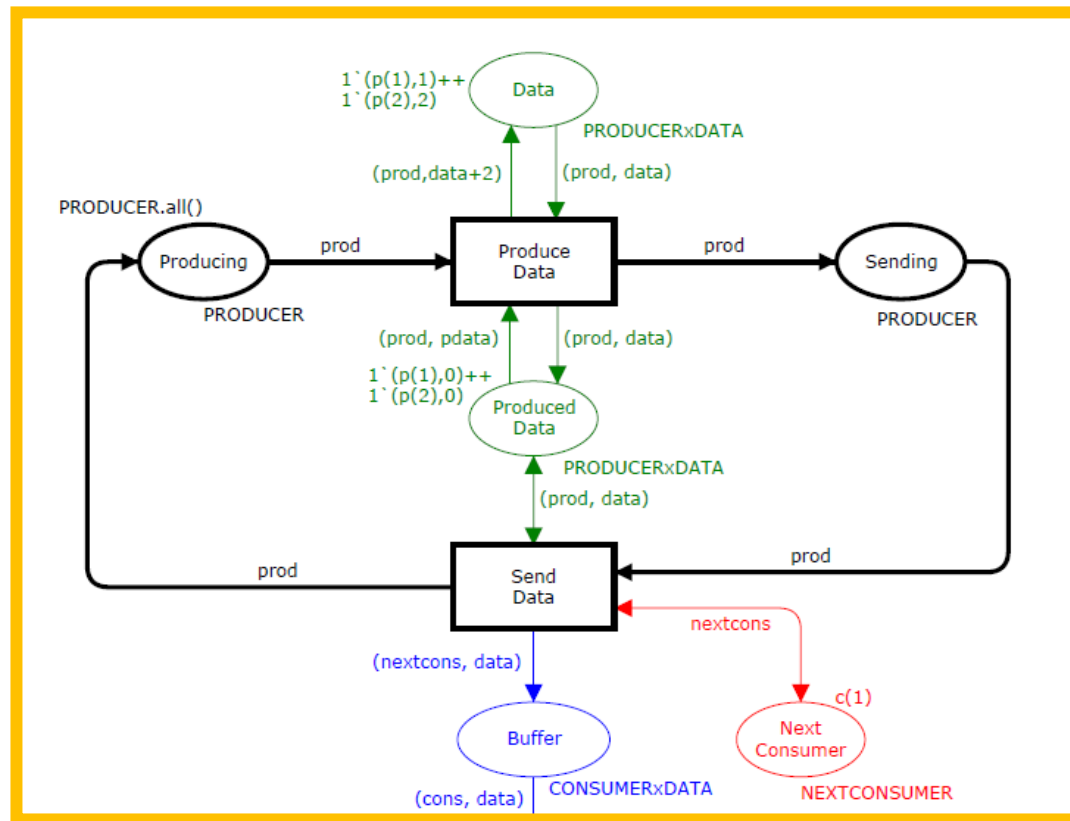
- The two last phases are target programming language specific:



- The **Erlang programming language** was used as the target programming language.
- The code generation did not consider the sequential CPN ML parts of the CPN model.

Phase 1: CPN Model Decoration

- Identification of **process partitions**, **process-**, **local-**, **buffer-** and **shared-** places.



Process partitions: Program executed by one or more processes.

Process places: Control flow locations of processes

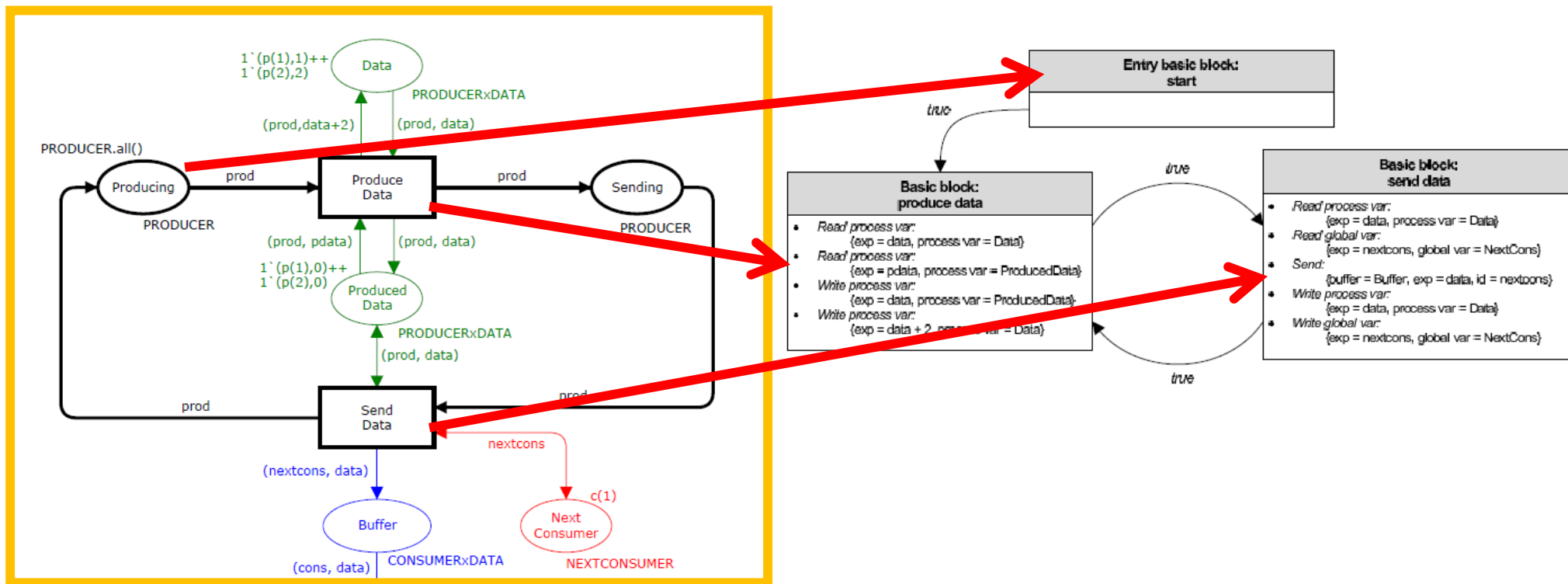
Local places: data local to a process.

Buffer places: messages passed to a process.

Shared places: data shared between processes.

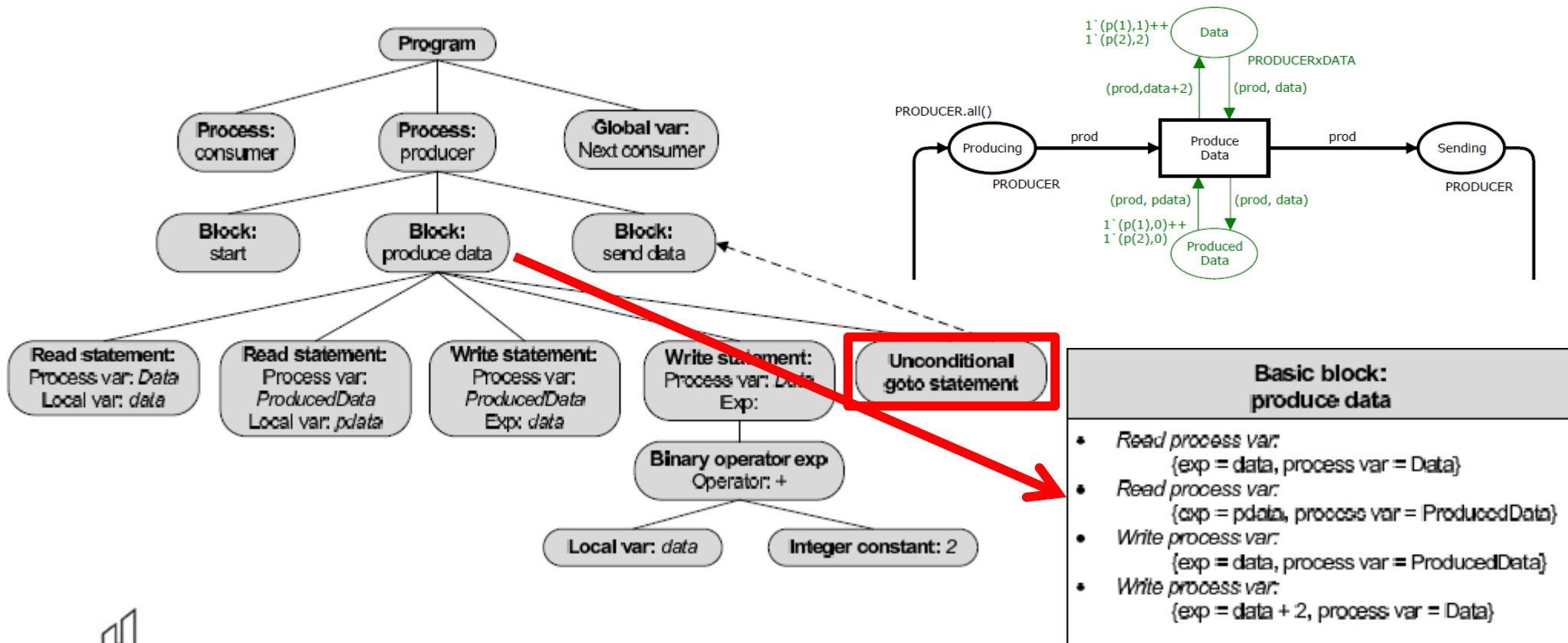
Phase 2: Translating to CFG

- Constructs a **control-flow graph** for each process partition:



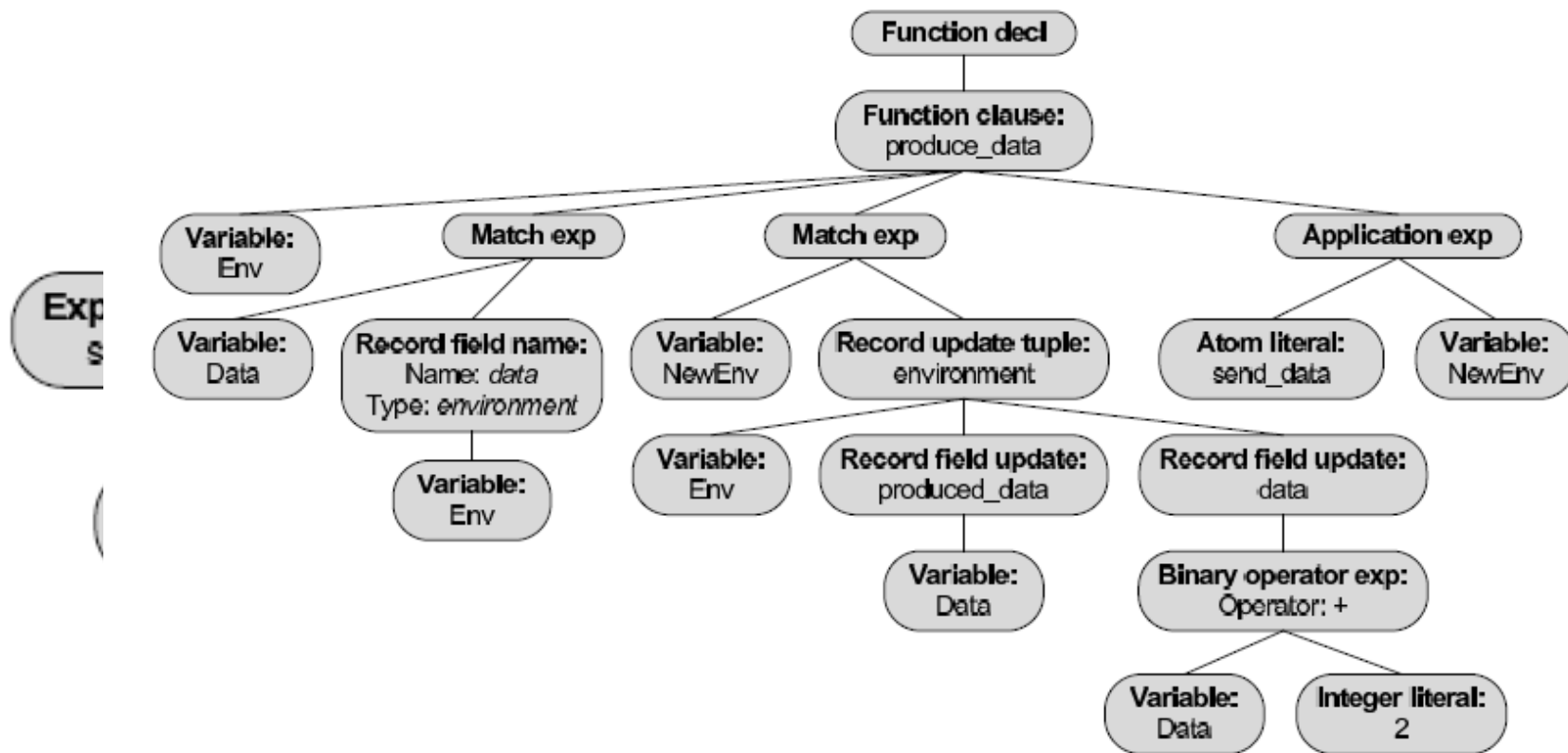
Phase 3: CFG to AST Translation

- Translates blocks and statements of the CFG into an abstract syntax tree (AST):



Phase 4: AST to EST Translation

- Generates an Erlang syntax tree (EST) from the abstract syntax tree (AST):



Phase 5: EST to Erlang Code

- Traverse the EST and writes out a textual representation of the Erlang program:

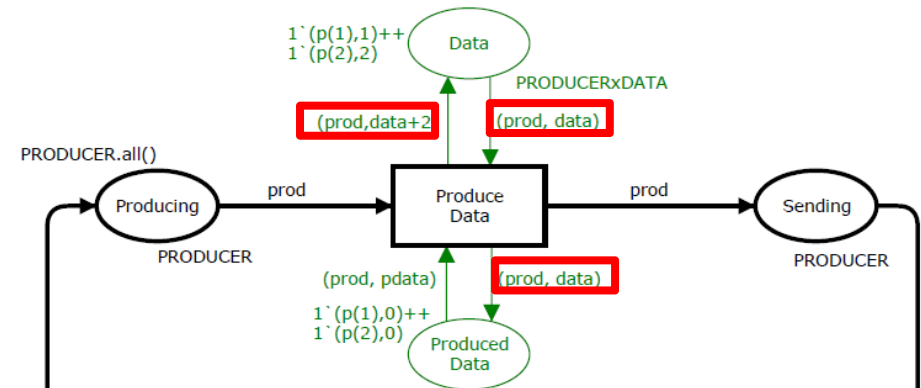
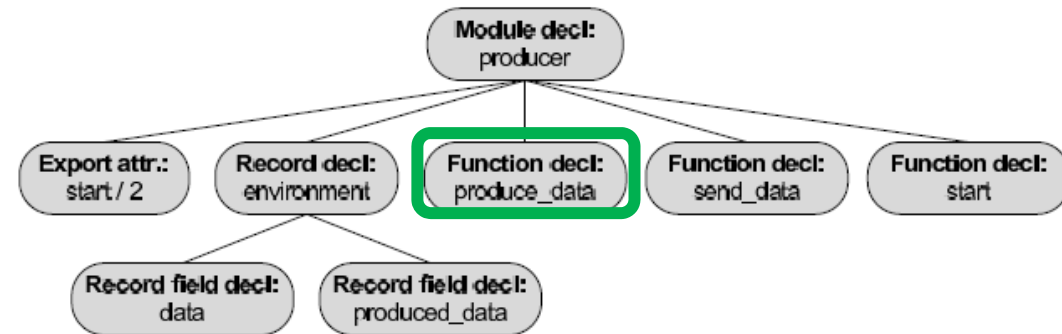
```
- module(producer).  
- export([start/2]).  
- record(environment, {  
  produced_data,  
  data}).
```

```
produce_data(Env) ->
```

```
→ Data = Env#environment.data,
```

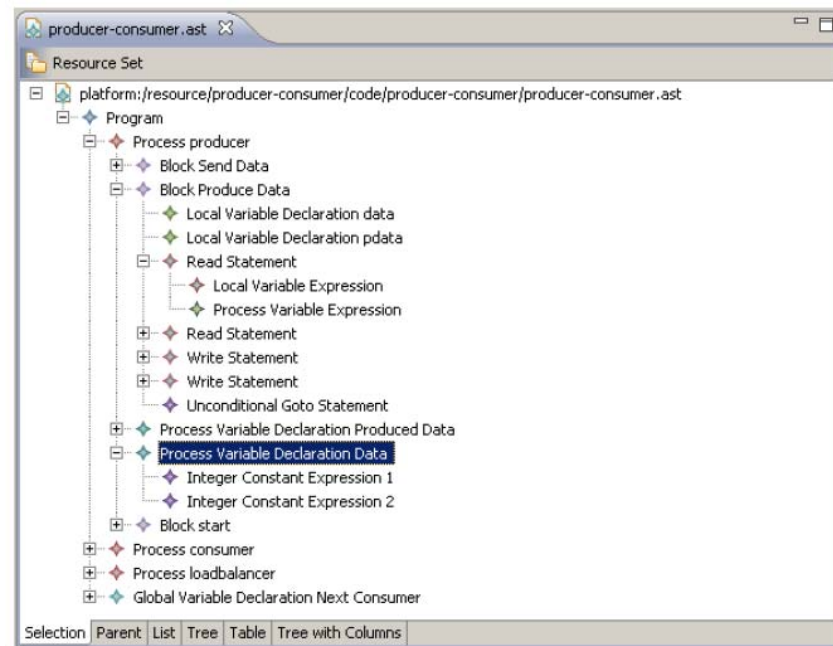
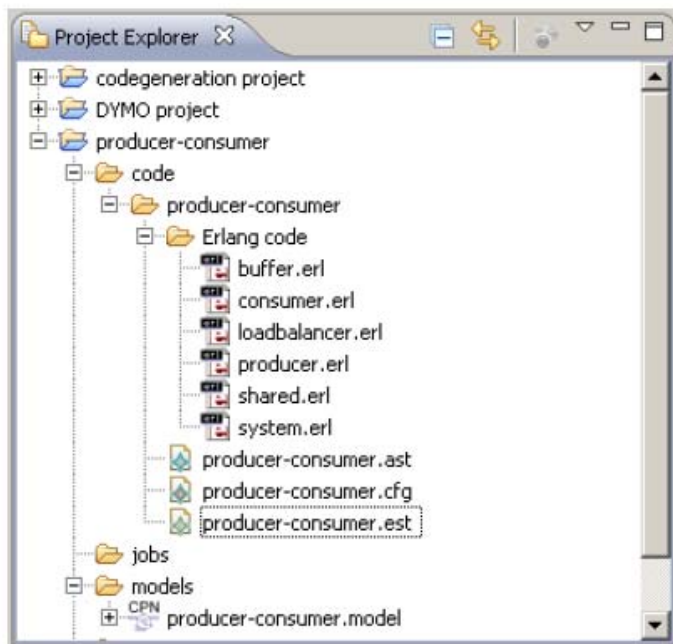
```
→ NewEnv = Env#environment {produced_data = Data,  
                             data = Data + 2},
```

```
send_data(NewEnv).
```



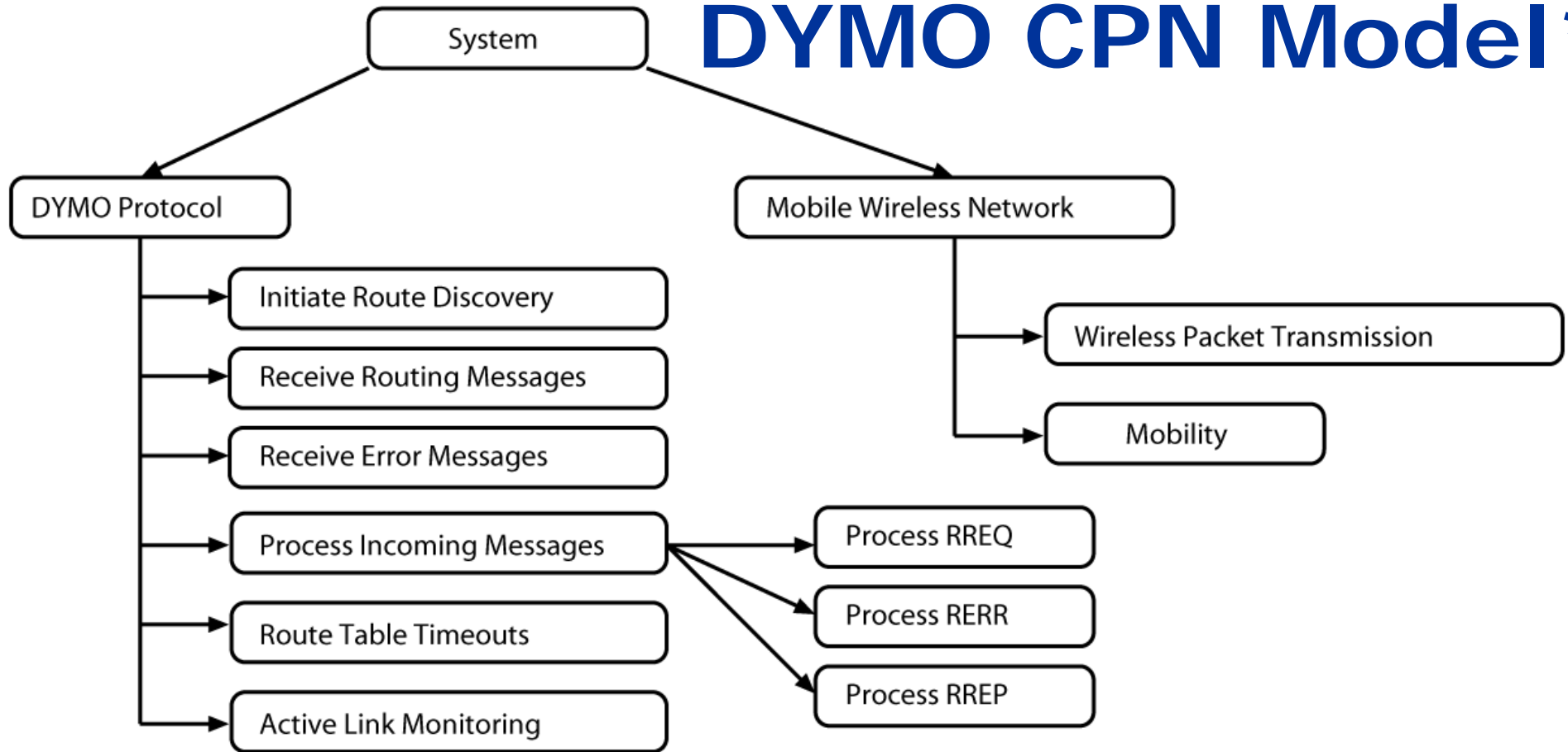
Computer Tool Support

- A prototype implementation realised as an Eclipse plug-in to the ASAP Verification Platform.
- The existing EMF CPN model of ASAP and the CPN importer was used to load CPN models:



A Larger Example: The DYMO MANET Routing Protocol

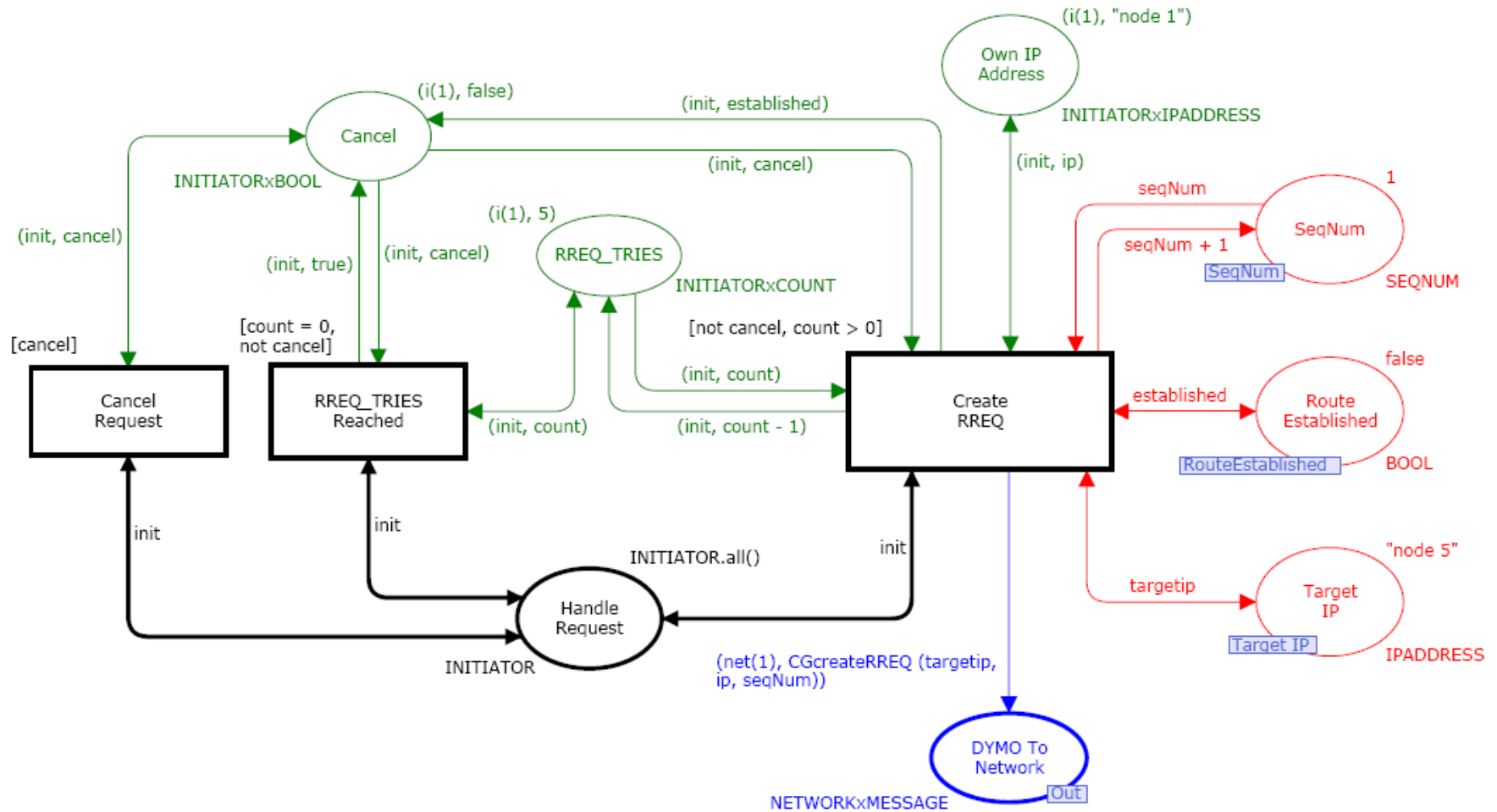
DYMO CPN Model*



- **Adjusted to satisfy the syntactical constraints of Process-Partitioned CPNs in approximately 20 person-hours.**

*K. L. Espensen, M. K. Kjeldsen, and L.M. Kristensen. Modelling and Initial Validation of the DYMO Routing Protocol for Mobile Ad-Hoc Networks. In Proc. of ICATPN'2008. Vol. 5062 of LNCS, pp. 152-170. Springer, 2008.

Example: Initiate Module



Code Generation and Validation

- **Statistics from code generation:**

Module name	L.O.C.	Functions to implement
system.erl	20	0
buffer.erl	36	0
shared.erl	16	0
initiator.erl	116	1
receiver.erl	116	7
processor.erl	111	4
establishchecker.erl	126	0
network.erl	22	0
Total	563	12

- **Approximately 12 person-hours for manual implementation of the sequential functions.**

- **The generated code was validated by setting up a distributed Erlang system:**

- Executes a set of Erlang nodes (run-time systems) on a single PC.
- Nodes communicate by means of an underlying network simulator.
- Each Erlang node independently executes the generated DYMO protocol entity implementation.

Conclusions and Future Work

- **A proof-of-concept for structure-based code generation has been established:**
 - Erlang programming language used as target language.
 - Applied on an large example: the DYMO Routing Protocol.
- **Main ideas for code generation:**
 - Introduce a CPN model class with explicit notions of control flow, messaging passing, and shared and local data.
 - Translation divided into five phases deferring the choice of the target programming language.
- **Some directions for future work:**
 - Extending the Process-Partitioned CPN model class.
 - Improve control structure recognition and maybe use GCC GENERIC as the target language.