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CENTER FOR MASSIVE DATA ALGORITHMICS


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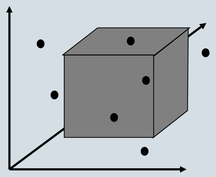
Orthogonal Range Reporting: Optimal 3-d Structures and Query Lower Bounds

Problem

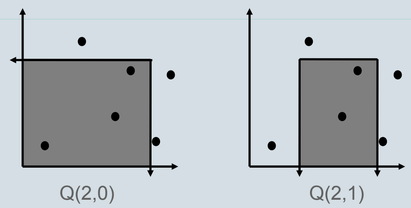
Input: n points in d dimensional space.



Support reporting the t points in a query box.

Variations

Query range may be unbounded in some dimensions:

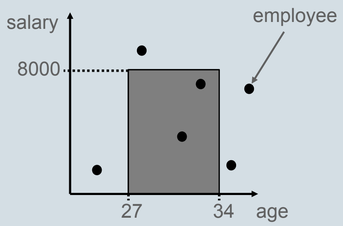


Q(d,k): d dimensional points, query ranges are finite in k dimensions.

Why important: more efficient solutions.

Motivation

Database queries:



"Give me all employees of age between 27 and 34, earning at most 8000 per month."

Results

The best previous result:

Type	Query	Space
Q(2,1)	**lg$n$+t**	**n**
Q(2,2)	**lg$n$+t**	**n lg$n$/lglg$n$**
Q(3,0)	**lg$n$+t**	**n**
Q(3,1)	**lg$n$+t**	**n lg$n$/lglg$n$**
Q(3,2)	**lg$n$+t**	n (lg$n$/lglg$n$)^2
Q(3,2)	lg^2n/lglg$n$+t	**n lg$n$/lglg$n$**
Q(3,3)	**lg$n$+t**	n (lg$n$/lglg$n$)^3
Q(3,3)	lg^2n/lglg$n$+t	**n (lg$n$/lglg$n$)^2**
Q(d,d)	lg$n$(lg$n$/lglg$n$)$^{d-3}$+t	n (lg$n$/lglg$n$)^d
Q(d,d)	lg$n$(lg$n$/lglg$n$)$^{d-2}$+t	**n (lg$n$/lglg$n$)$^{d-1}$**

Bounds in **bold** are optimal.
Space lower bound $\Omega(n(\lg n/\lg\lg n)^{d-1})$.
No query lower bound beyond $\Omega(\lg n+t)$.

We achieve:

Type	Query	Space
Q(2,1)	**lg$n$+t**	**n**
Q(2,2)	**lg$n$+t**	**n lg$n$/lglg$n$**
Q(3,0)	**lg$n$+t**	**n**
Q(3,1)	**lg$n$+t**	**n lg$n$/lglg$n$**
Q(3,2)	**lg$n$+t**	**n lg$n$/lglg$n$**
Q(3,3)	**lg$n$+t**	**n (lg$n$/lglg$n$)^2**
Q(d,d)	lg$n$(lg$n$/lglg$n$)$^{d-3}$+t	**n (lg$n$/lglg$n$)$^{d-1}$**

Bounds in **bold** are optimal. We also show the query time lower bound of $\Omega((\lg n/\lg\lg n)^{d/2-1}+t)$. Optimal solution for all 3-d variations.

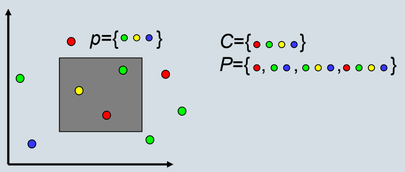
References

[1] Afshani, Arge, Larsen. *Orthogonal Range Reporting in Three and Higher Dimensions.* FOCS 2009.

[2] Afshani, Arge, Larsen. *Orthogonal Range Reporting: Query Lower Bounds, Optimal Structures in 3-d, and Higher-dimensional Improvements.* SoCG 2010.

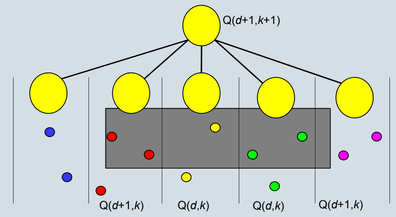
Concurrent Range Reporting

We solve harder variants of orthogonal range reporting.
We call these concurrent Q(d,k) (CQ(d,k)).



Points have colors from set of colors C.
Query: Q(d,k) box q + set of colors p from a set $P\subseteq 2^C$.
Must report points in q with color in p.

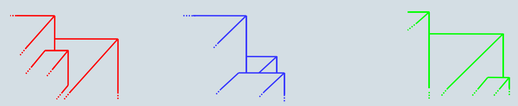
Solution for CQ(d,k) gives solution for Q(d,k+1) (and Q(d+1,k+1)) by paying lg$n$/lglg$n$ in space (and query time).



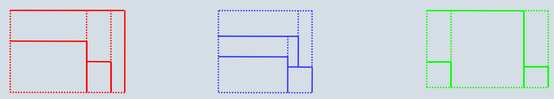
Range tree with fanout lg$^\varepsilon n$.
Q(d+1,k+1) becomes CQ(d,k) with colors { }.
Height of tree lg$n$/lglg$n$.

Solving Concurrent Q(3,0)

lg$n$-shallow cuttings: O(n/lg$n$) Q(3,0) boxes s.t. queries outputting < lg$n$ points are inside at least one box. Each box contains O(lg$n$) input points.



Build lg$n$-shallow cuttings for every color.
Store Q(3,0) structure inside each box, and for every color.

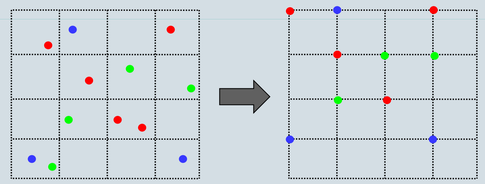


Given query q, find boxes containing it using 2-d point enclosure in time O(lg$n$+|C|).

For every color:
- If q inside a box b, query Q(3,0) structure inside b.
- Otherwise, query Q(3,0) structure on all points.

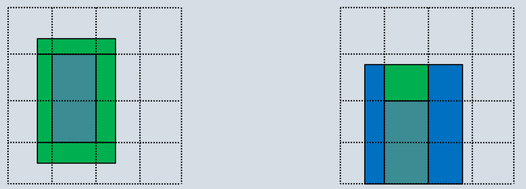
Solving Concurrent Q(3,2)

Query unbounded in z-dimension. Build grid on x and y dimensions.



The grid has size w by w where $w=\sqrt{n/|C||P|\lg^2 n}$.
n/w points in each horizontal and vertical slab.
Points snapped to grid.

Structures stored:
- CQ(3,0) structure on points in every slab.
- For every p in P, a Q(3,2) structure on points with least z coordinate from every color in every grid cell.
- Linked list for every color in every grid cell with points sorted by z coordinate.
- Recursive structure inside each slab.



Queries decompose into four CQ(3,1) queries and a grid query.
In recursive steps, they become one recursive CQ(3,1) query, two CQ(3,0) queries and one grid query.