Verifying Programs that Manipulate Pointers

Anders Møller



http://www.brics.dk/~amoeller/talks/infinity.pdf

<u>Heap</u>: *an untidy pile or mass of things* [Cambridge Dictionary]

- This is how most program analyses view the heap
- because pointers are notoriously difficult to reason about
- but they are an important part of most programming languages...

Example: Reversing a Linked List

```
struct Node {
 struct Node *n;
 int data;
}
Node *reverse(Node *x) {
 Node *y, *t;
 y = NULL;
 while (x != NULL) {
  t = y;
  y = x;
  x = x - >n;
  y -> n = t;
 }
 return y;
```

Assume that the input is an acyclic list, argue that

- there are no null pointer dereferences
- no elements are lost
- the output is an acyclic list
- the output is the reverse of the input
- no other parts of the heap are modified

Verifying Programs that Manipulate Pointers

In addition to the usual problems with software verification,

- destructive updating through pointers (x->f = y) can make complex structures
- the heap has **unbounded size**
- data-structure invariants typically only hold at the beginning and end of operations

- Separation Logic (Reynolds & O'Hearn)
 - an extension of Hoare logic
- Parametric Shape Analysis (Sagiv, Reps & Wilhelm)
 - data-flow analysis using three-valued logic
- **Pointer Assertion Logic** (Møller & Schwartzbach)
 - using monadic second-order logic on trees

Hoare Logic



- partial correctness: if S is executed in a store initially satisfying P and it terminates, then the final store satisfies Q
- the *assertion language* is typically predicate logic with transitive closure or inductively defined predicates

Hoare Logic and Pointers

Consider the standard axiom for assignment:

This is unsound in presence of pointers!



A possible solution?

Idea: view the heap as an array for each field

This works, but forces *global reasoning*

- every heap assignment seems to affect every heap assertion

Consider a possible loop invariant:

 $\exists \alpha, \beta$: LIST[α](x) ∧ LIST[β](y) ∧ $\alpha_0^{\mathsf{R}} = \alpha^{\mathsf{R}} \cdot \beta$

Unfortunately, it is **not enough**:

- we must explicitly forbid sharing between the x and y lists
- we must explicitly state that every other part of the heap is unaffected!
 - this makes modular specifications impossible

Separation Logic

New assertions:

- emp
- $E \mapsto F_1:E_1,...,F_n:E_n$
- P * Q
- P -* Q

(empty heap)
(one-cell heap)
(separating conjunction)
(separating implication)

Axiom for assignment to the heap ("mutation"):

$$\overline{\{\mathsf{X} \mapsto \rho, \mathsf{F}:_,\sigma\}} \quad \mathsf{X}{\operatorname{->}\mathsf{F}} = \mathsf{E}; \qquad \{\mathsf{X} \mapsto \rho, \mathsf{F}:\mathsf{E},\sigma\}$$

Axiom for assignment from the heap ("lookup"):

 $\{ \mathsf{Y} \mapsto \rho, \mathsf{F}: \mathsf{V}, \sigma \} \quad \mathsf{X} = \mathsf{Y}_{\mathsf{->}}\mathsf{F}; \quad \{ \mathsf{X} = \mathsf{V} \land \mathsf{Y} \mapsto \rho, \mathsf{F}: \mathsf{V}, \sigma \}$

- variants for backwards reasoning also exist

- allocation/disposal, pointer arithmetic, etc., also works

The Frame Rule, Local Reasoning

{P} S {Q} {P * R} S {Q * R}

- all heap cells that are not mentioned in the specification are guaranteed to remain unchanged!
- many other new inference rules...
- now the loop invariant works immediately for the list reversal example: ∃α,β: (LIST[α](x) * LIST[β](y)) ∧ α₀^R= α^R·β

Parametric Shape Analysis

Automatic inference of "shape invariants" using data-flow analysis with three-valued logic

Representing Concrete Stores using Logic

A logical structure consists of

- a **universe** of elements
- a family of basic **predicates**

- let the universe represent the set of heap cells
- each variable x is described by a unary predicate x(p)
- each field f is described by a *binary* predicate f(p,q)

Example of a Logical Structure



is described by the logical structure whose universe is {a,b,c,d} and the basic predicates are interpreted by:

	a	b	С	d	_	f	а	b	С	d	_	g	а	b	С	d
x	1	0	0	0		а	0	1	0	0		а	0	0	0	0
v	0	1	0	0		b	0	0	1	0		b	0	1	0	0
			-	•		С	0	0	0	1		С	0	0	0	0
						d	0	0	0	0		d	0	0	0	0

Queries

Queries are expressed in *first-order logic with transitive closure*

- Are x and y pointer aliases?
 ∃p: x(p) ∧ y(p)
- Does x point to a cell with a self cycle?
 ∃p: x(p) ∧ n(p,p)
- Do x and y refer to disjoint structures?
 ¬∃p,q,r: x(p) ∧ y(q) ∧ n*(p,r) ∧ n*(q,r)

Operational Semantics by Predicate Transformation

Statements that modify the store can be described using *predicate transformation*:

- x = NULL x'(p) = 0
- x = y x'(p) = y(p)
- x = y f $x'(p) = \exists q: y(q) \land f(q,p)$
- $y \rightarrow f = x$ $f'(p,q) = (y(p) \land x(q)) \lor (\neg y(p) \land f(p,q))$

How can this be used as a basis for program analysis?

- Idea: use the standard data-flow analysis framework with the lattice being sets of logical structures
- however, the concrete structures have unbounded size (the lattice needs to have finite height)...
- we need some **abstraction**!

Canonical Abstraction

Collapse elements that cannot be distinguished by unary predicates



- the lattice of sets of these abstract structures is finite!

Kleene's 3-Valued Logic

- 0 = false/never
- 1 = true/always
- $1/_2 = \text{don't know}$

Abstract Structures are 3-Valued Logic Structures



- a 3-valued structure S represents a set of 2-valued structures {T₁, T₂, ...}
- evaluating a query formula Φ on S is a conservative approximation of evaluating it on any ${\rm T_i}$

The Analysis - Abstract Interpretation

- The lattice consists of sets of 3-valued structures
- Concrete **operational semantics** is defined using predicate transformation on **2**-valued structures
- Abstract **transfer functions** can be defined using predicate transformation on **3**-valued structures

Instrumentation Predicates

- How do we distinguish cyclic lists from acyclic lists?
- or recognize disjoint lists?
- or handle doubly-linked lists?
- or ...?
- Allow extra "instrumentation predicates" to be defined (in terms of the core predicates)
- Canonical abstraction considers all unary predicates, including instrumentation predicates!

Examples of Instrumentation Predicates

is_n(p) = ∃q,r: n(q,p) ∧ n(r,p) ∧ q ≠ r
 do two or more n fields point to p?



r_{x,n}(p) = ∃q: x(q) ∧ n*(q,p)
 is p reachable from x through n fields?



c_{f,g}(p) = ∀q,r: f(p,q) ∧ g(q,r) ⇒ p=r
 does an f dereference from p followed by a g dereference yield p?



Using Instrumentation Predicates

- The **choice** of instrumentation predicates depends on the application
- Adding instrumentation predicates improves precision
 but decreases worst-case performance
- Predicate transformation for instrumentation predicates must also be defined - and proven sound relative to the core predicates

- Instrumentation predicates:
 - $r_{x,n}(p), r_{y,n}(p), r_{t,n}(p)$ ("reachability along n from x/y/t")
 - is_n(p) ("pointed to by more than one n field")
 - c_n(p) ("cycle along n fields")
- Input structure: x → (r_{x,n}) ∩ (r_{x,n}) ; n
- Running the TVLA tool:
 - fixed point found after 4 iterations
 - output structure: $y \rightarrow r_{y,n} \cdots \rightarrow r_{y,n} \cdots \rightarrow n$
 - i.e., all cells are moved from x to y without introducing loops!

- Describe stores using graph types and monadic second-order logic on trees (M2L-Tree)
- Split the programs into Hoare triples without loops and procedure calls using explicit invariants
- Encode each triple as an M2L-Tree formula and run the MONA decision procedure
- relation to Separation Logic: everything is decidable here
- relation to Parametric Shape Analysis: no abstraction, explicit invariants

List Reversal, revisited

```
struct Node { struct Node *n; int data; }
pred ROOTS(pointer x,y:Node, set R:Node) =
allpos p of Node: p in R <=> x<n*>p | y<n*>p
Node *reverse(Node *x)
 set R:Node [ROOTS(x,NULL,R)]
{
 Node *y, *t;
 y = NULL;
 while (x != NULL) [ROOTS(x,y,R)] {
  t = y;
                                     In 0.5 secs., the PALE tool verifies that
  V = X;
  x = x - >n;

    all nodes are moved

  y -> n = t;

    no cycles are introduced

 }

    there can be no memory errors

 return y;
}[ROOTS(NULL,return,R)]
```

M2L-Tree and Graph Types

- M2L-Tree:
 - monadic second-order logic
 - on tree structures
- Graph types:
 - tree structures specified by recursive types
 - with extra pointers specified by M2L-Tree formulas

Pointer Assertion Logic: M2L-Tree + Graph types

- allows many common heap structures to be expressed (doubly-linked lists, trees with parent pointers, etc.)
- reducible to M2L-Tree and decidable

Encoding Hoare triples in M2L-Tree

Use *transductions* to encode loop-free code:

- Store predicates model the store at each program point
- **Predicate transformation** models the semantics of statements Example: $\mathbf{x} = \mathbf{y} \cdot \mathbf{next}; \rightarrow \mathbf{x}'(p) = \exists q \cdot \mathbf{y}(q) \land \mathbf{next}(q,p)$
- Verification condition is constructed by expressing the pre- and post-condition using store predicates from end points
- Each triple is then verified separately (by the MONA tool)
- If invalid, a concrete counterexample store is generated!

Summary / Conclusion

Reasoning about programs that use pointers is challenging...

Separation Logic

- Hoare logic with *separating conjunction*
- supports local reasoning and often permits succinct proofs

Parametric Shape Analysis

- *data-flow analysis* where stores are represented abstractly using *three-valued logical structures*
- allows precision/performance to be controlled by the choice of *instrumentation predicates*
- Pointer Assertion Logic
 - decidable application of Hoare logic
 - requires *invariants*, but high expressiveness and modularity
- Still at research level, not really practically useful (yet?)

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- Separation Logic: A Logic for Shared Mutable Data Structures J.C. Reynolds, LICS 2002
- Parametric Shape Analysis via 3-Valued Logic
 M. Sagiv, T. Reps, and R. Wilhelm, TOPLAS 20(1)
- The Pointer Assertion Logic Engine
 A. Møller and M.I. Schwartzbach, PLDI 2001