

...the branch of engineering that develops technology for automated inference

--- Cosma Shalizi

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Flavors of Learning



(Binary) classification

Given: $\{(\mathbf{x_1}, y_1), (\mathbf{x_2}, y_2), \ldots\}$ drawn from some source $\mathbf{x_i} \in \mathbb{R}^d$ $y_i \in \{+1, -1\}$ Find a function $f : \mathbb{R}^d \mapsto \{+1, -1\}$ such that f captures the relationship between \mathbf{x} and y $\forall i, f(x_i) = y_i$









- Spam: Testing if email is spam or not
- Sentiment analysis: is a product review positive or negative

Regression

Given:
$$\{(\mathbf{x_1}, y_1), (\mathbf{x_2}, y_2), \ldots\}$$
 drawn from some source
 $\mathbf{x_i} \in \mathbb{R}^d \quad y_i \in \mathbb{R}$

Find a function $f : \mathbb{R}^d \mapsto \mathbb{R}$

such that f captures the relationship between x and y $\forall i, f(x_i) = y_i$



Regression Given: $\{(\mathbf{x} | \mathbf{x})\}$ Find a funct such that

7.4 C. H. H. C.



- Predictions: Stock market price as function of financial specs
- Relationship between dosage and effectiveness

Unsupervised Learning

Clustering



Given a collection of objects, find a way to "group" them into similar pieces

Learning a function $f : \mathbb{R}^d \mapsto \{1, 2, \dots, k\}$

But we don't have any examples of the "correct" answer ! Clustering is closely related to classification with multiple classes

Unsupervised Learning



Given a collection of objects, find a way to "group" them into similar pieces

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Unsupervised Learning

Dimensionality Reduction (or Feature Learning)



Given objects in \mathbb{R}^d find a mapping $A : \mathbb{R}^d \mapsto \mathbb{R}^k, k \ll d$ that preserves the "structure" of the objects

- Find "relevant" dimensions for a task
- Reduce dimensionality to manage complexity of algorithms

Mixing and Matching

Semi-supervised learning: labelled and unlabeled data



Find a classifier that separates the labeled points and separates the unlabeled points "well"

Often have lots of unlabeled data and only a little labeled data to guide efforts

Mixing and Matching

Supervised clustering = multiclass classification



Supervised dimensionality reduction = (linear) discriminant analysis



Understanding vs Predicting

 $\{(\mathbf{x_1}, y_1), (\mathbf{x_2}, y_2), \ldots\}$ is drawn from distribution $p(\mathbf{X}, Y)$

Generative learning: Learn the distribution $p(\mathbf{X}, Y)$

"What controls the rise and fall of the tides ?"

Discriminative learning: Learn the <u>conditional</u> distribution $p(Y | \mathbf{X})$

"Will there be a high tide tomorrow evening ?"

$$p(Y \mid \mathbf{X}) = \frac{p(\mathbf{X}, Y)}{p(\mathbf{X})}$$

Understanding vs Predicting

Discriminative clustering: predict the cluster of a new point





Understanding vs Predicting

Discriminative clustering: predict the cluster of a new point



Generative clustering: mixture density estimation





Parameters

Parametric Learning:

- Define a space of models parametrized by fixed number of parameters
- Find model that best fits the data (by searching over parameters)

Parametric binary classification:

• Model: $(\mu_1, \Sigma_1, \mu_2, \Sigma_2)$

$$p(\mathbf{x}) \propto \exp(-(\mathbf{x} - \boldsymbol{\mu})^{\top} \Sigma(\mathbf{x} - \boldsymbol{\mu}))$$

- Maximize likelihood of any model
- $d^2 + 2d$ parameters





Parameters

Non-parametric Learning:

- Define a space of models that can grow in size with data.
- Find model that best fits the data
- "Non-parametric" means "Not-fixed", not "none" !



4 "support points" define the resulting classifier.

Bayesian Learning

Non-Bayesian (parametric) learning:





Bayesian Learning

Non-Bayesian (parametric) learning:



 Θ^* is a point estimate. $\hat{p}(\Theta)$ is a distribution over possible worlds

Bayesian Learning

You know you're talking to a Bayesian if...





Many Learning Frameworks

- Online Learning: must make prediction as soon as item arrives
- Active Learning: I can get labels for data, but it's expensive.
- Multi-task Learning: I'm learning different tasks, but they're related so maybe the tasks can learn from each other.
 - Transfer Learning: I can learn well in one domain: can I transfer this
 - knowledge into a different domain ?
 - Ensemble Learning: I have bad learners, but together they're decent



The Mechanics of Learning



Loss Functions

Given: $\{(\mathbf{x_1}, y_1), (\mathbf{x_2}, y_2), \ldots\}$ drawn from some source $\mathbf{x_i} \in \mathbb{R}^d$ $y_i \in \{+1, -1\}$ Find a function $f : \mathbb{R}^d \mapsto \{+1, -1\}$ such that f captures the relationship between \mathbf{x} and yLoss functions $L(f((\mathbf{x}), y))$ measure the quality of f: $\mathbf{1}_{f(\mathbf{x}) \neq y}$



Estimating Risk

Once we have a loss function, we can quantify how good a predictor is:

$$R(f) = E_{\mathbf{x},y}[L(f(\mathbf{x}), y)] = \int p(\mathbf{x}, y)L(f(\mathbf{x}), y)$$

and find a good predictor:

$$f^* = \arg\min_{f\in\mathcal{F}} R(f)$$

But we don't usually know what the data distribution is, so we can't solve the minimization !



Empirical Risk Minimization

Assume the given data is drawn from the source distribution. Replace

$$R(f) = E_{\mathbf{x},y}[L(f(\mathbf{x}), y)] = \int p(\mathbf{x}, y)L(f(\mathbf{x}), y)$$

by the empirical mean:

$$\hat{R}(f) = \frac{1}{n} \sum_{i} L(f(\mathbf{x}_i, y_i))$$

with the hope that the estimate is unbiased and converges:

$$E[\hat{R}(f)] = R(f), \quad \hat{R}(f) \to R(f)$$

But now we have a "normal" optimization:

$$\min_{f\in\mathcal{F}}\frac{1}{n}\sum_{i}L(f(\mathbf{x}_{i},y_{i})$$

Overfitting and Regularization



The problem with optimizing over the data is that you can over-fit to your samples. (low bias)

This is bad because then your predictive power goes down (high variance) and you can't generalize

Complex models (with more parameters) can overfit. Penalize them !

$$\min_{f \in \mathcal{F}} \frac{1}{n} \sum_{i} L(f(\mathbf{x}_i, y_i) + c(f))$$

model complexity term

This is called regularization.

Generalization

How many samples of the data do you need for the empirically optimized answer to get close to the true answer ?

If your function space is "well behaved" (not too wiggly), then you don't need too many samples.

Well behaved:

- VC dimension is small
- Rademacher complexity is small
- Fat shattering dimension is small
- ... and others.

All of this assumes that you sample from the real distribution...

Overview... so far...

- 1) Choose a learning task (classification, clustering, regression, ...)
- 2) Pick a convenient loss function
- 3) Sample a sufficient number of points from a source
- 4) Build an optimization using the data, the loss function, and any regularizers
- 5) OPTIMIZE !!!
- 6) Use learned model on new data to predict.
- 7) (if you're doing online learning, repeat)



The Computational Geometry prayer: Let P be a set of points in the plane. Amen.



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But in learning, we don't have a "natural" representation. We have to CHOOSE one.



Representations help algorithms



Learning a circle separating classes can be tricky



Representations help algorithms



Learning a circle separating classes can be tricky

If we change the representation

$$\ell:(x,y)\mapsto (x,y,x^2+y^2)$$



Representations help algorithms



Learning a circle separating classes can be tricky



Constructing a representation

Supervision guides the representation



And many other kinds...











